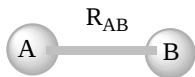


Moments of Inertia of Common Molecules

Linear

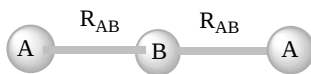
Diatomic $I_c = I_b > I_a = 0$

$$I = \frac{m_A m_B}{m_A + m_B} R_{AB}^2$$



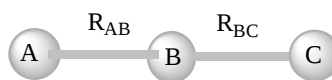
Symmetric Triatomic

$$I = 2m_A R_{AB}^2$$



Non-symmetric Triatomic

$$I = m_A R_{AB}^2 + m_C R_{BC}^2 - \frac{(m_A R_{AB} - m_C R_{BC})^2}{m_A + m_B + m_C}$$

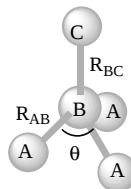


Symmetric Rotors $I_c = I_b > I_a$ (Prolate symmetric rotor)
 $I_c > I_b = I_a$ (Oblate symmetric rotor)

Type A_3BC

$$I_a = 2m_A R_{AB}^2 (1 - \cos \theta)$$

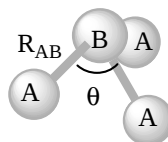
$$I_c = m_A R_{AB}^2 (1 - \cos \theta) + \frac{m_A}{\sum m_i} (m_B + m_C) R_{AB}^2 (1 + 2 \cos \theta) + \frac{m_C R_{BC}^2}{\sum m_i} \left\{ (3m_A + m_B) R_{BC} + 6m_A R_{AB} \left[\frac{1}{3} (1 + 2 \cos \theta) \right]^{1/2} \right\}$$



Type A_3B

$$I_a = 2m_A R_{AB}^2 (1 - \cos \theta)$$

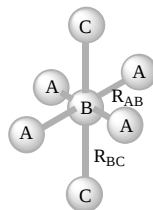
$$I_c = m_A R_{AB}^2 (1 - \cos \theta) + \frac{m_A m_B}{\sum m_i} R_{AB}^2 (1 + 2 \cos \theta)$$



Type A_4BC_2

$$I_a = 4m_A R_{AB}^2$$

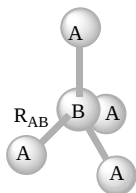
$$I_c = 2m_A R_{AB}^2 + 2m_C R_{BC}^2$$



Spherical Rotors $I_c = I_b = I_a$

Tetrahedral

$$I = \frac{8}{3} m_A R_{AB}^2$$



Octahedral

$$I = 4m_A R_{AB}^2$$

